

A Novel MIP-based Airspace Sectorization for TMAs

Tobias Andersson Granberg, Tatiana Polishchuk, Christiane Schmidt

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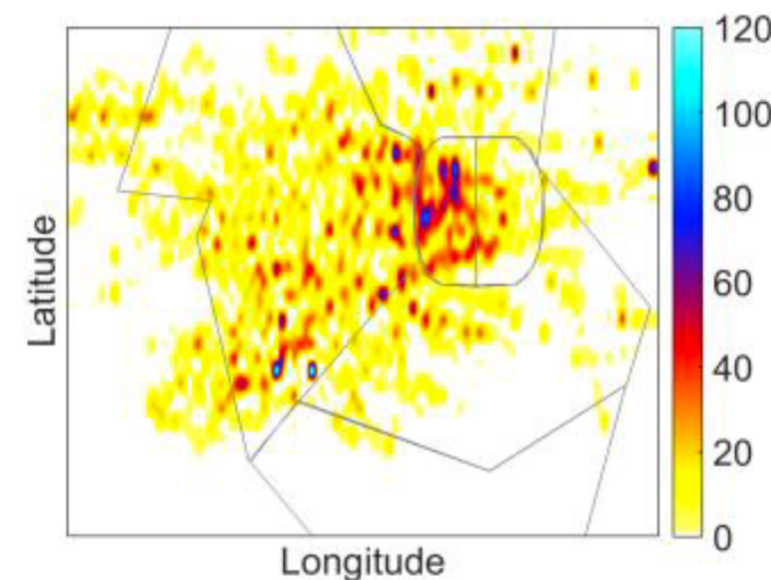
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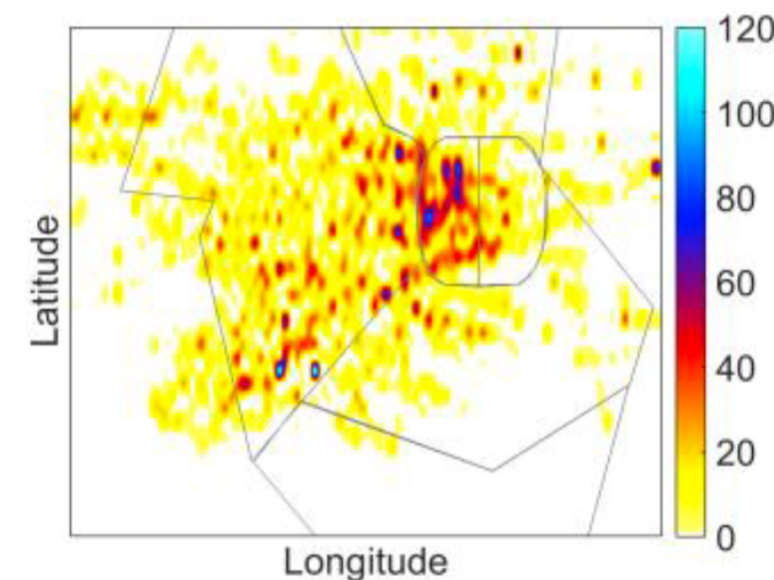
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- Taskload: objective demands of the ATCO's monitoring task
- We use heat maps of the density of weighted clicks as an input [Zohrevandi et al., 2016].
- BUT: we do not depend on specific maps.



A **sectorization** of a simple polygon P is a partition of P into k disjoint subpolygons S_1, \dots, S_k ($S_i \cap S_j = \emptyset \ \forall i \neq j$), such that $\bigcup_{i=1}^k S_i = P$.

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(g) Interior conflict points (Points that require increased attention from ATCOs should lie in the sector's interior.)

Grid-based IP formulation

- © Square grid in the TMA

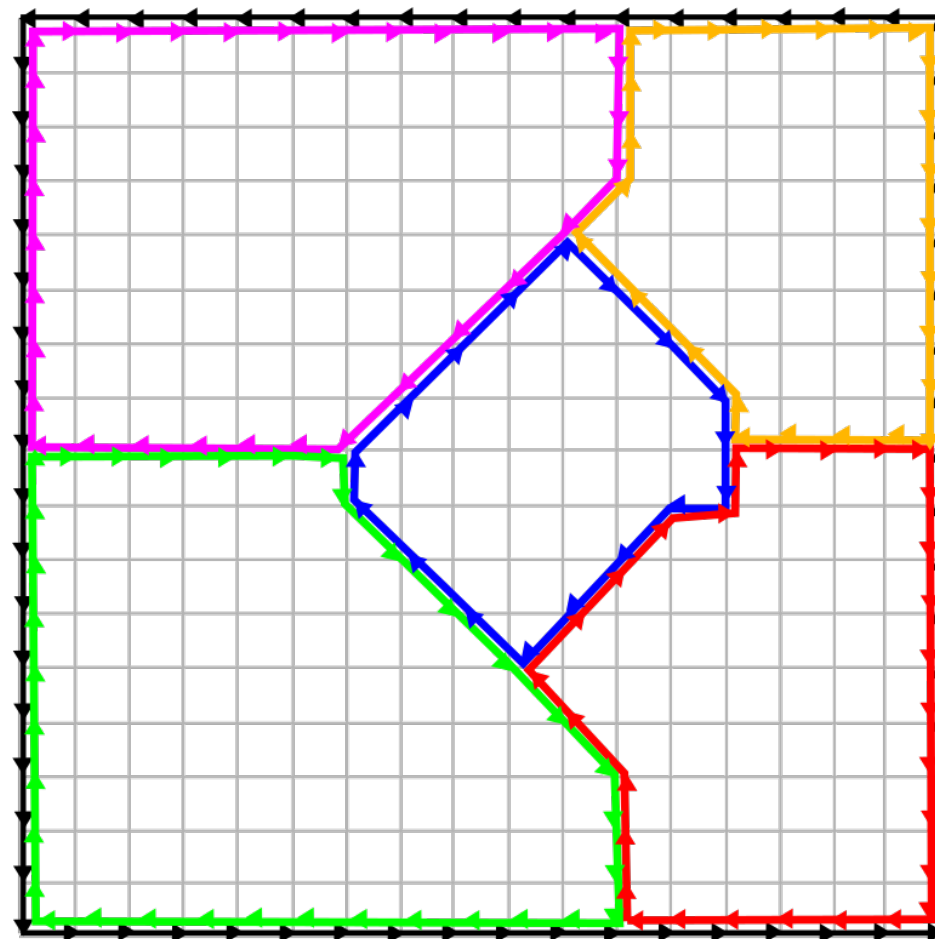
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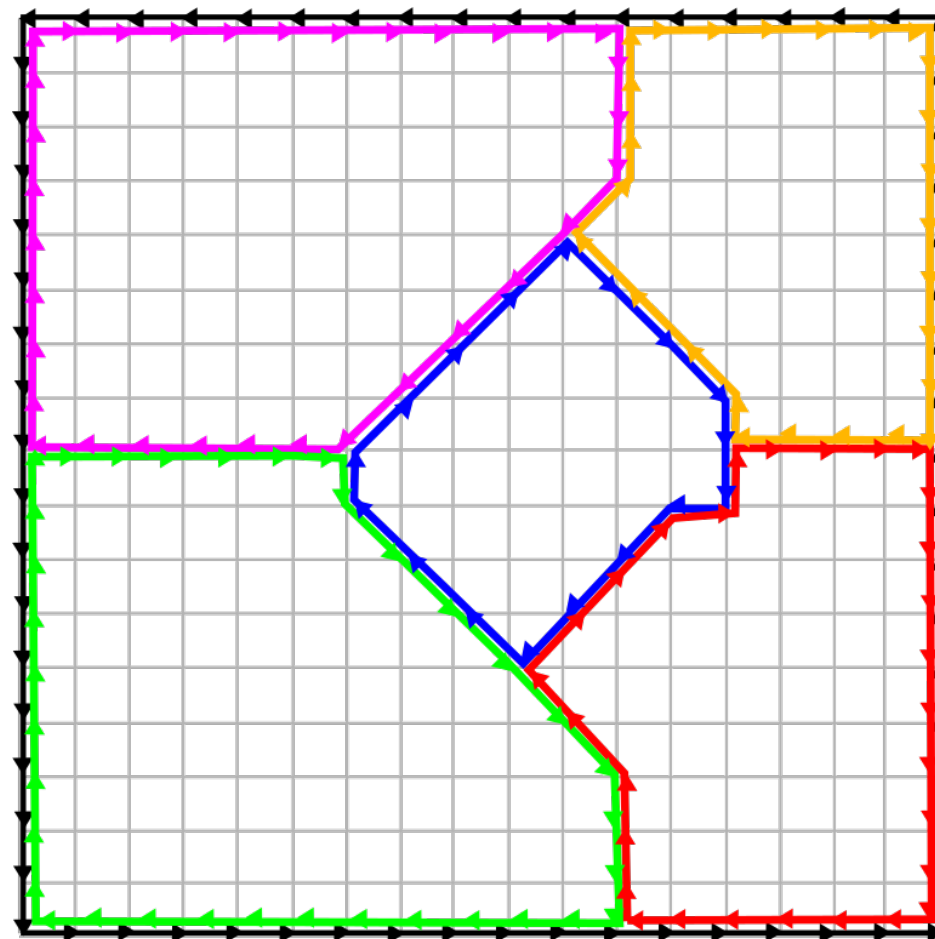
Main idea: use an artificial sector, S_0 , that encompasses the complete boundary of P , using all counterclockwise (ccw) edges.



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Main idea: use an artificial sector, S_0 , that encompasses the complete boundary of P , using all counterclockwise (ccw) edges.

We use sectors in $S^* = S \cup S_0$ with $S = \{S_1, \dots, S_k\}$.



$y_{i,j,s} = 1$: edge (i,j) used for sector s

$$y_{i,j,0} = 1 \quad \forall (i,j) \in S_0$$

$$\sum_{s \in \mathcal{S}^*} y_{i,j,s} - \sum_{s \in \mathcal{S}^*} y_{j,i,s} = 0 \quad \forall (i,j) \in E$$

$$y_{i,j,s} + y_{j,i,s} \leq 1 \quad \forall (i,j) \in E, \forall s \in \mathcal{S}^*$$

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$$\sum_{l \in V: (l,i) \in E} y_{l,i,s} \leq 1 \quad \forall i \in V, \forall s \in \mathcal{S}^*$$

A node has at most one ingoing edge per sector

$y_{i,j,s} = 1$: edge (i,j) used for sector s

| | | | | |
|---------------------------------------------------------------------------------|---|----------------------------------------------------|---------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------|
| $y_{i,j,0} =$ | 1 | $\forall (i,j) \in S_0$ | All ccw boundary edges in S_0 | |
| $\sum_{s \in \mathcal{S}^*} y_{i,j,s} - \sum_{s \in \mathcal{S}^*} y_{j,i,s} =$ | 0 | $\forall (i,j) \in E$ | If (i,j) used for some sector, (j, i) has to be used as well. |  (i,j) in S_i , (j,i) has to be in another sector |
| $y_{i,j,s} + y_{j,i,s} \leq$ | 1 | $\forall (i,j) \in E, \forall s \in \mathcal{S}^*$ | Sector cannot contain (i,j) and (j,i). | |
| $\sum_{s \in \mathcal{S}^*} y_{i,j,s} \leq$ | 1 | $\forall (i,j) \in E$ | No edge in two sectors. | |
| $\sum_{(i,j) \in E} y_{i,j,s} \geq$ | 3 | $\forall s \in \mathcal{S}^*$ | Minimum size | |
| $y_{i,j,s} \in \{0, 1\} \quad \forall (i,j) \in E, \forall s \in \mathcal{S}^*$ | | | | |

| | | | |
|-----------------------------------------------------------------------------------|---|------------------------------------------------|------------------------------------------------|
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\Rightarrow Union of the $|\mathcal{S}|$ sectors completely covers the TMA.

(a) Balanced size

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We need to assign area to sector selected by boundary edges!

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Area of polygon P with rational vertices and can be computed efficiently [Fekete et al., 2015]:

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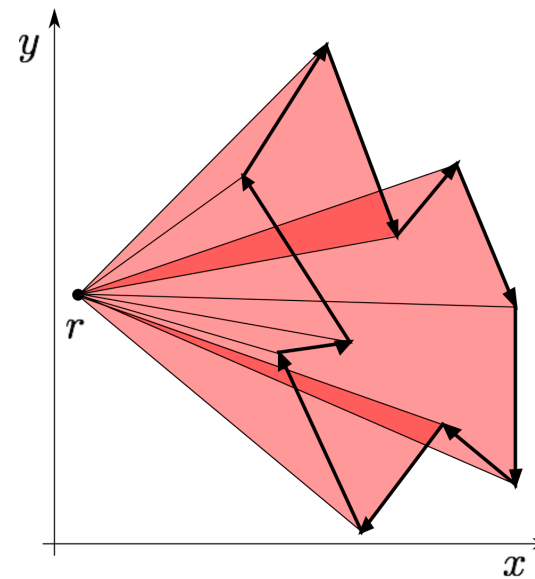
- We introduce reference point r .
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 - cw triangles contribute positive

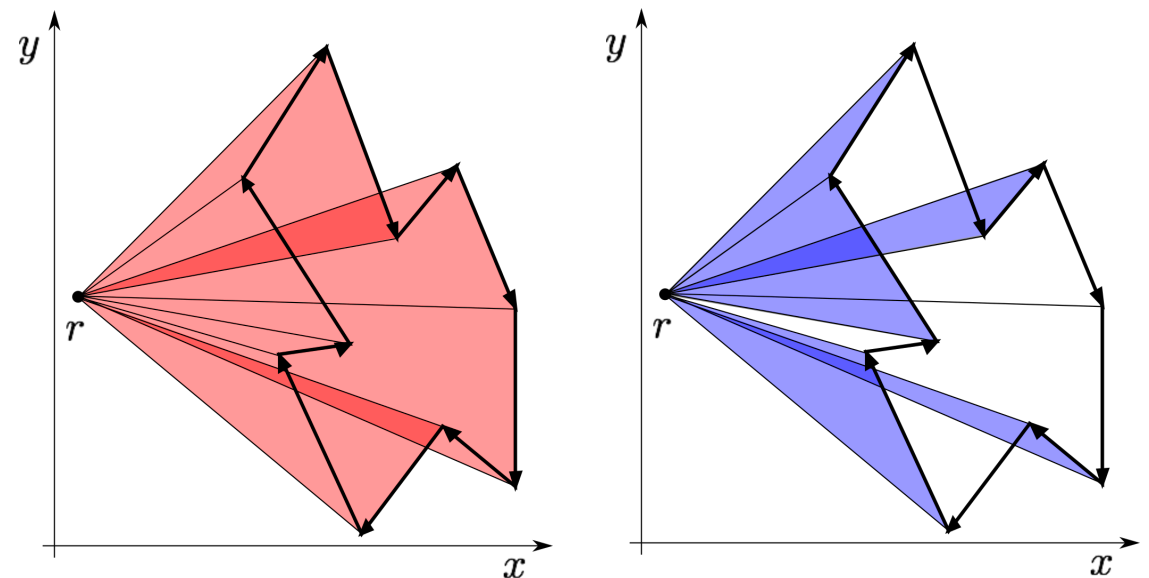


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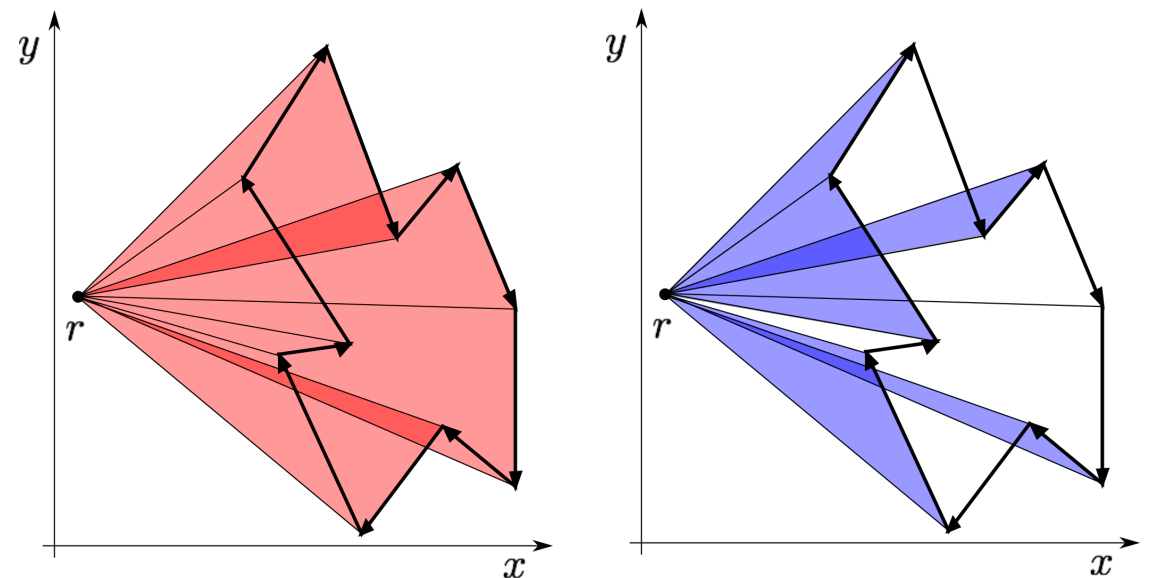


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- $f_{i,j}$: signed area of the triangle (i,j) and r

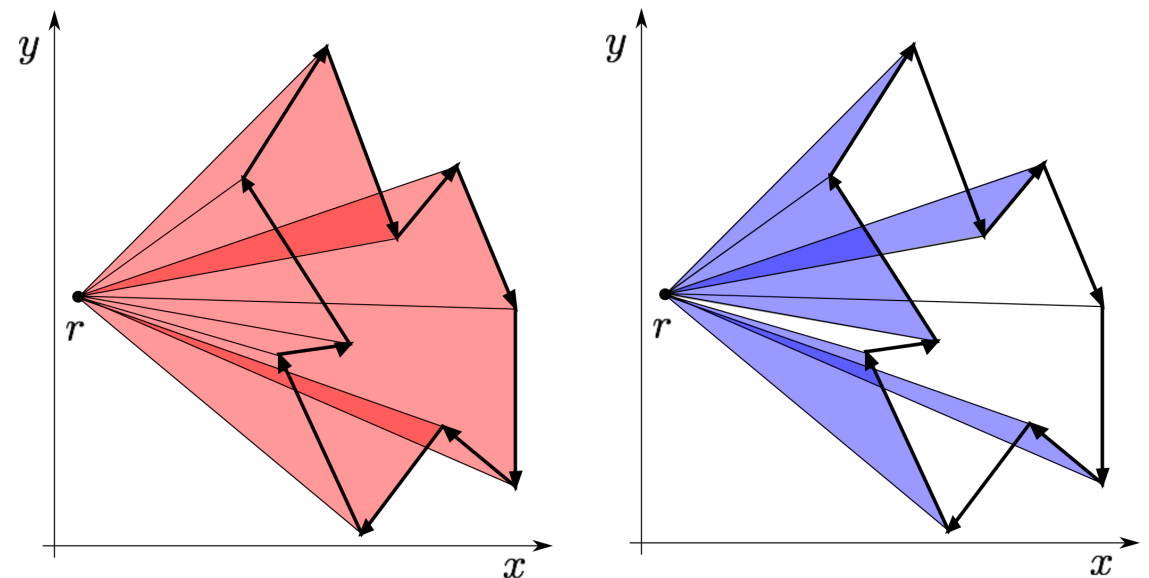


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$$\sum_{(i,j) \in E} f_{i,j} y_{i,j,s} - a_s = 0$$

$$\sum_{s \in \mathcal{S}} a_s = a_0$$

$\forall s \in \mathcal{S}^*$ Assigns area of sector s to a_s

$$a_s \geq a_{LB} \quad \forall s \in \mathcal{S}$$

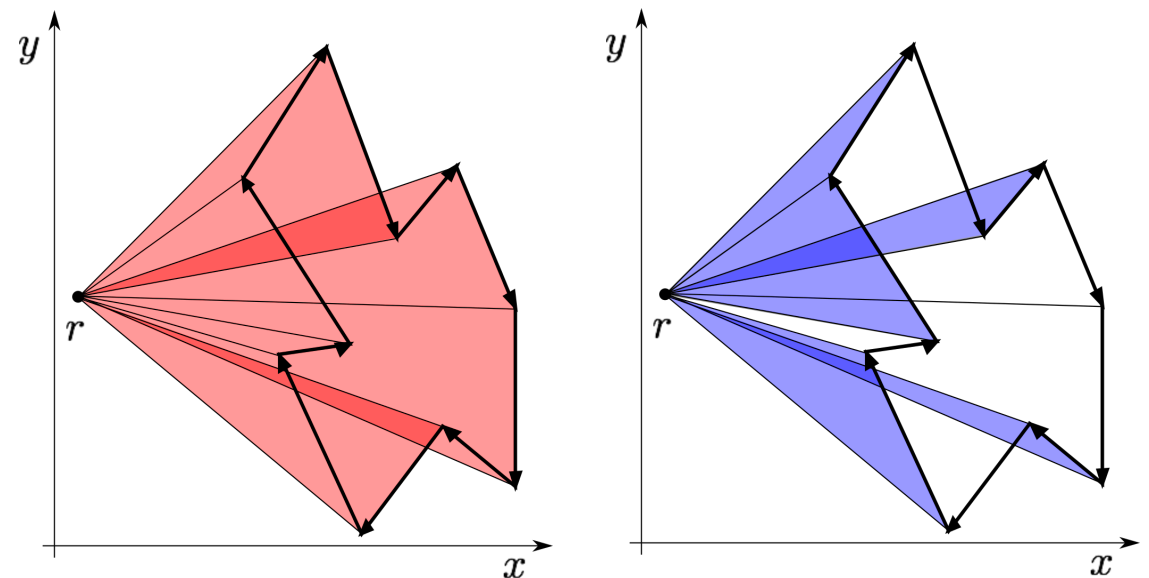
$$a_{LB} = c_1 \cdot a_0 / |\mathcal{S}|, \text{ with , e.g., } c_1 = 0.9$$

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Assigns area of sector s to a_s

Sum of areas = area of S_0

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(b) Bounded taskload/ (c) Balanced taskload

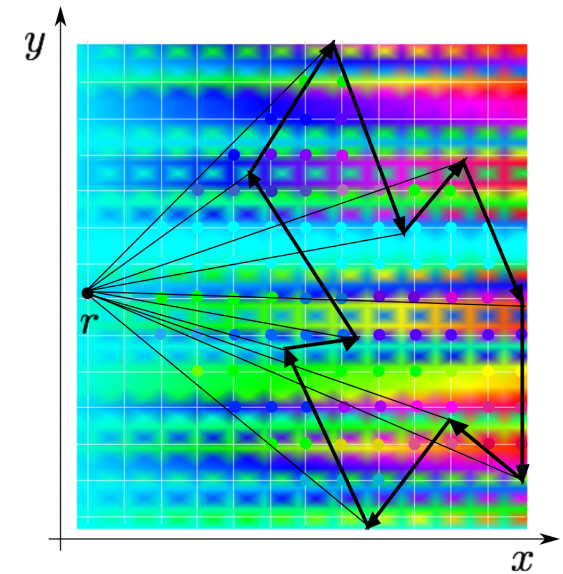
(b) Bounded taskload/ (c) Balanced taskload

We need to associate task load with a sector.

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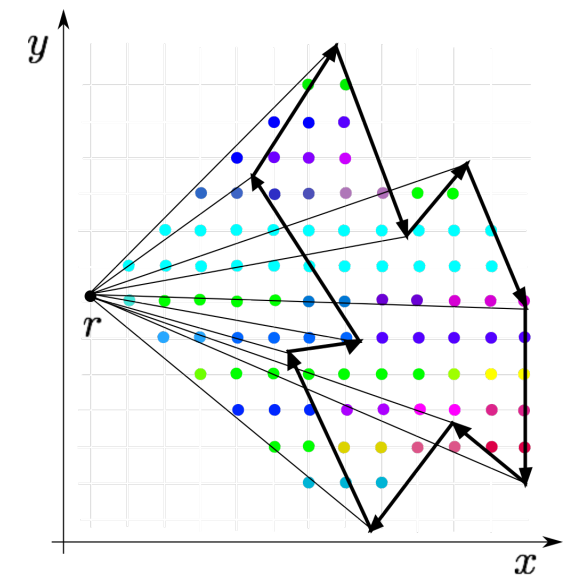
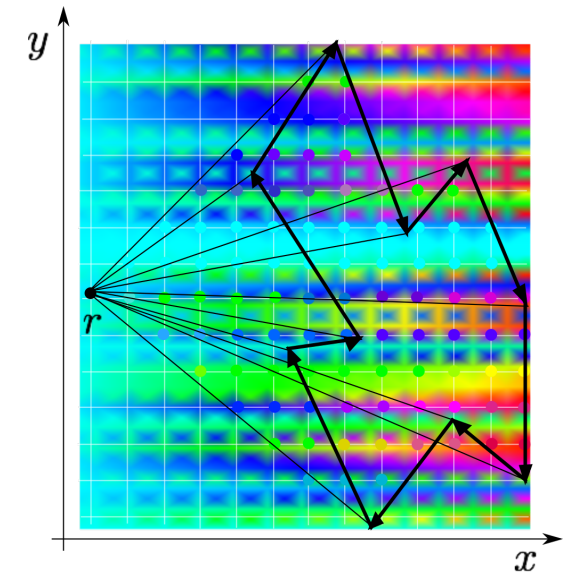
- Overlay heat map with a grid.



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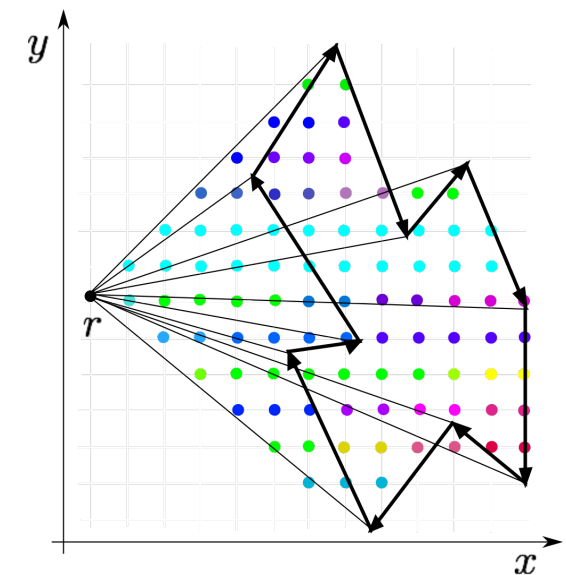
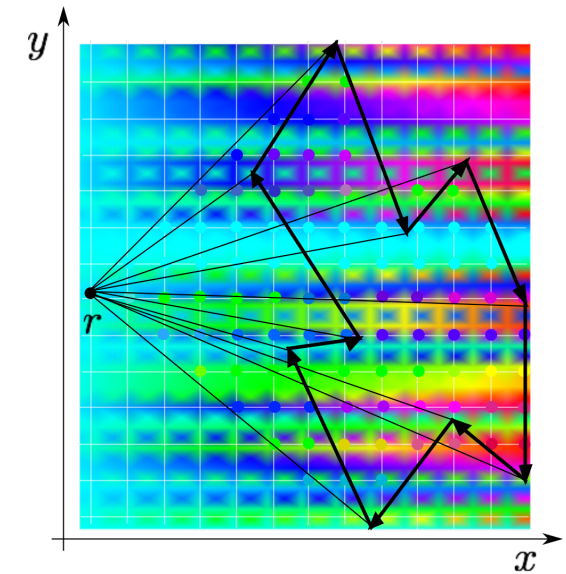
- Overlay heat map with a grid.
- Extract values at the grid points.



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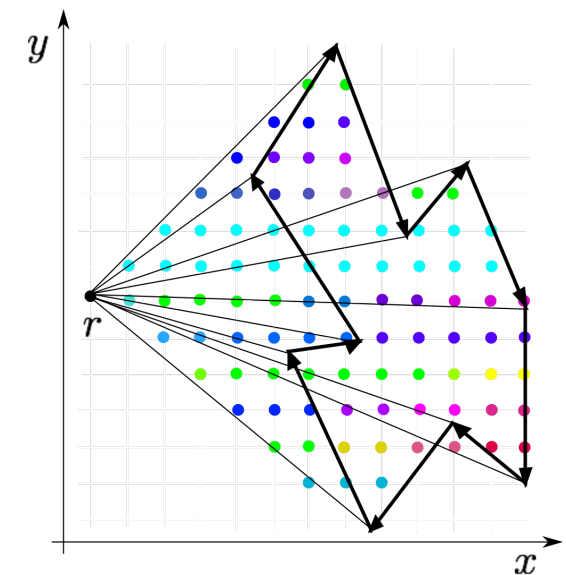
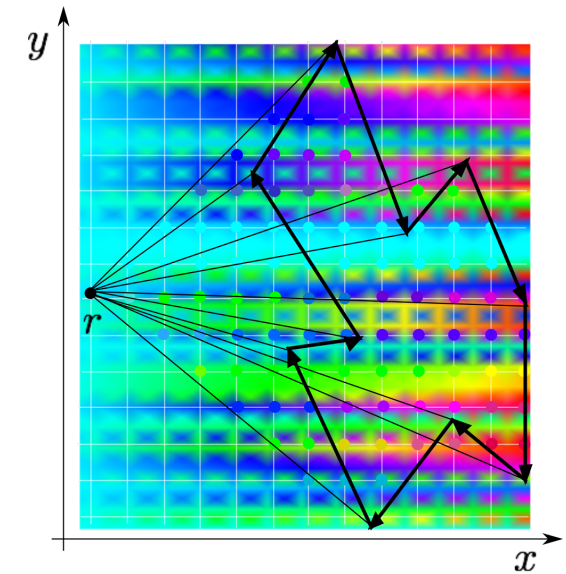
- Overlay heat map with a grid.
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- Use discretized heat map.



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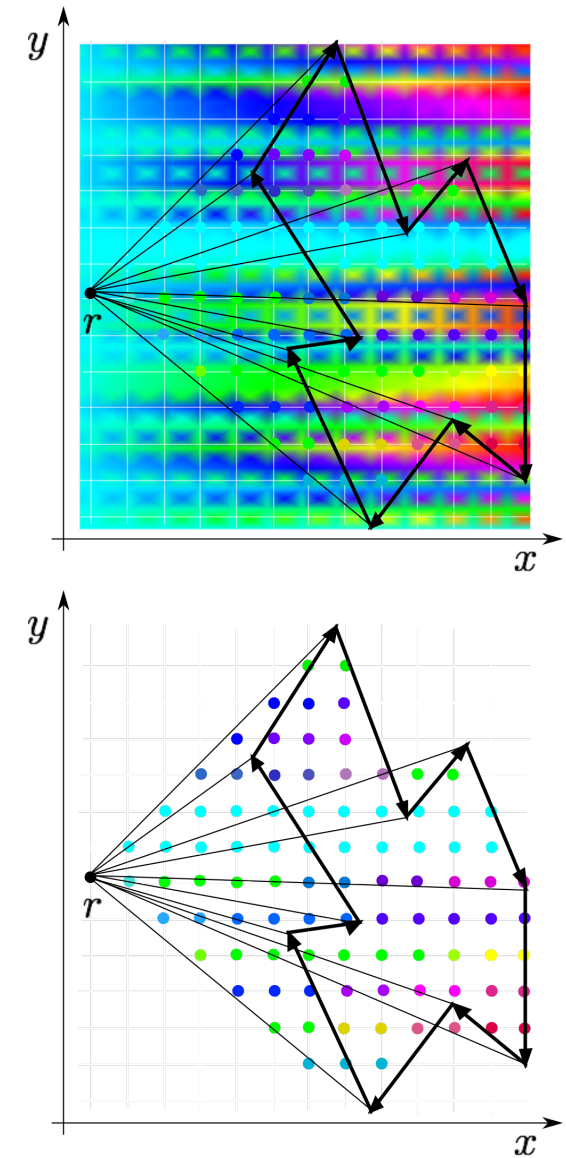
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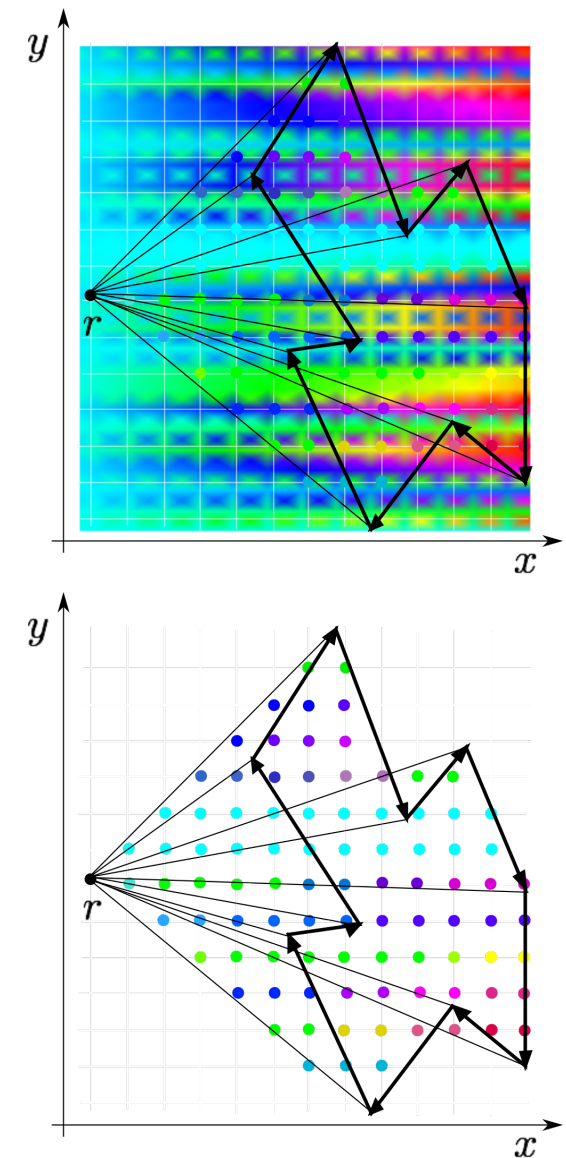
$$h_{i,j} = p_{i,j} \sum_{q \in \Delta(i,j,r)} h_q$$

$$\sum_{(i,j) \in E} h_{i,j} y_{i,j,s} - t_s = 0 \quad \forall s \in \mathcal{S}$$

$$t_s \geq t_{LB} \quad \forall s \in \mathcal{S}$$

$$t_s \leq t_{UB} \quad \forall s \in \mathcal{S}$$

$$t_{LB} = c_2 \cdot t_0 / |\mathcal{S}| \quad \text{with, e.g., } c_2 = 0.9$$



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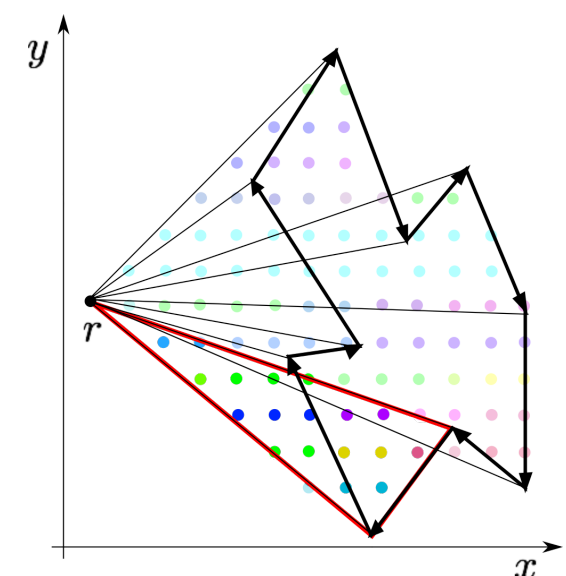
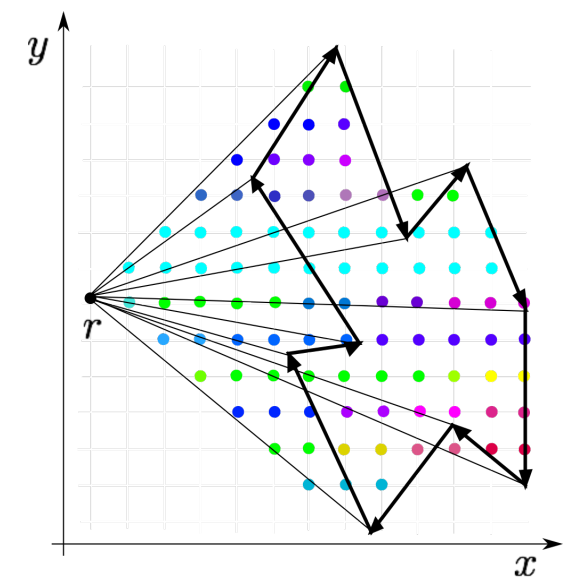
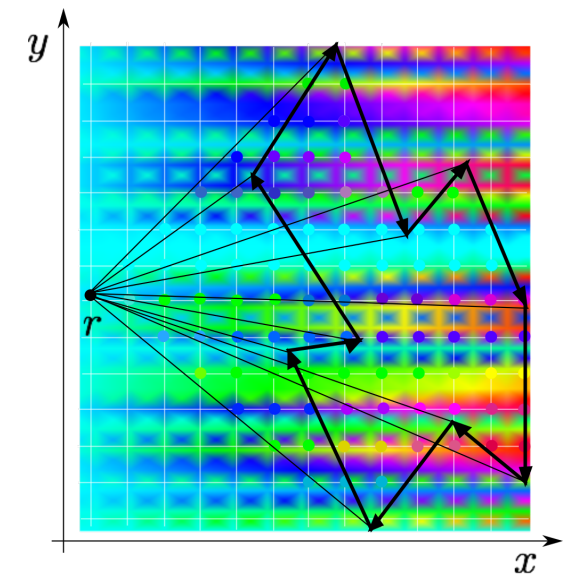
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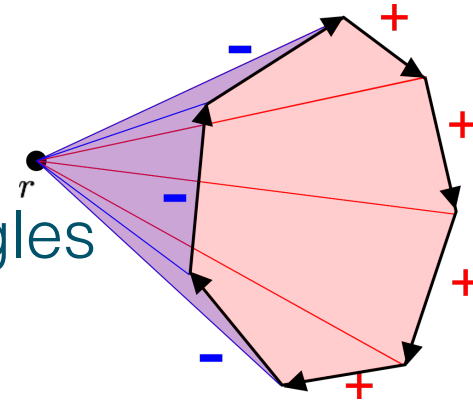
(f) Convex sectors

(f) **Convex sectors**

- Convex sector:

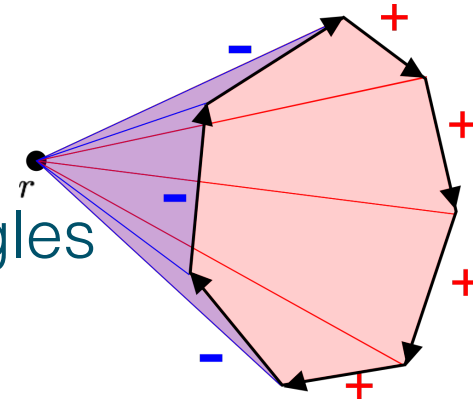
(f) Convex sectors

- Convex sector:
 - only one connected chain of edges with cw triangles



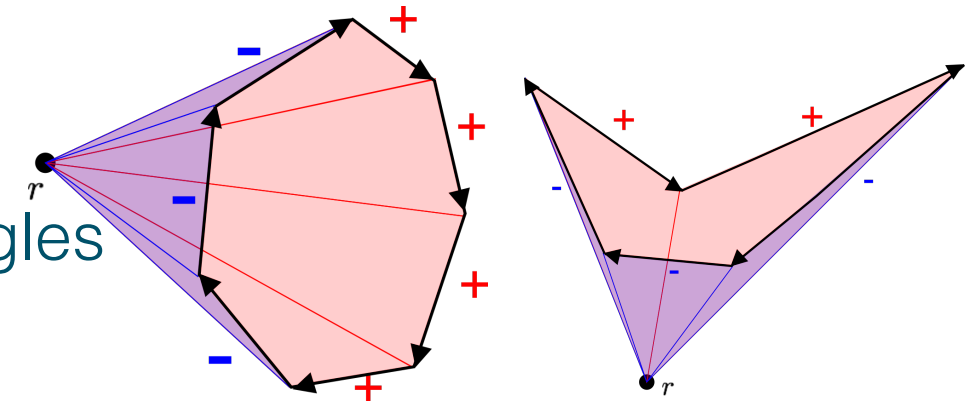
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- Convex sector:
 - only one connected chain of edges with cw triangles
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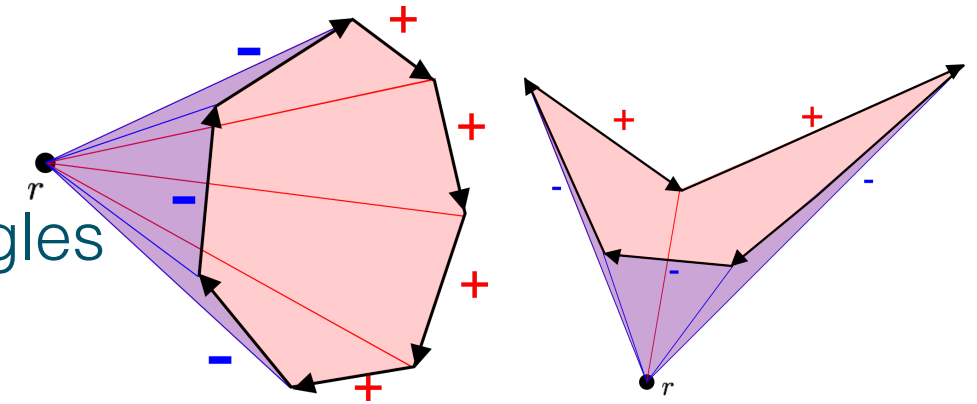
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- Convex sector:
 - only one connected chain of edges with cw triangles
 - one connected chain of edges with ccw triangles
- Only-if-part of that statement is not true



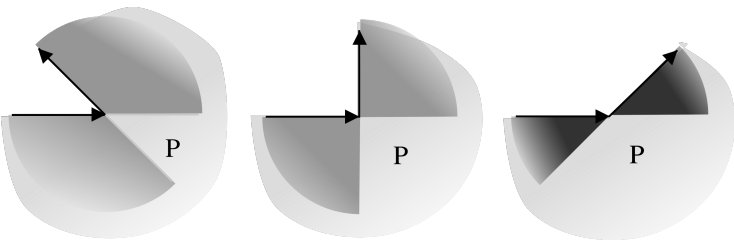
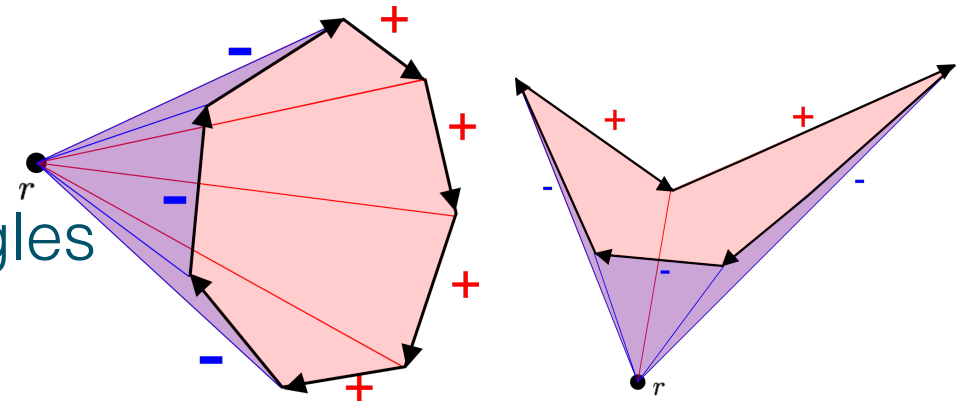
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- Convex sector:
 - only one connected chain of edges with cw triangles
 - one connected chain of edges with ccw triangles
- Only-if-part of that statement is not true
- BUT: we have only eight edge directions



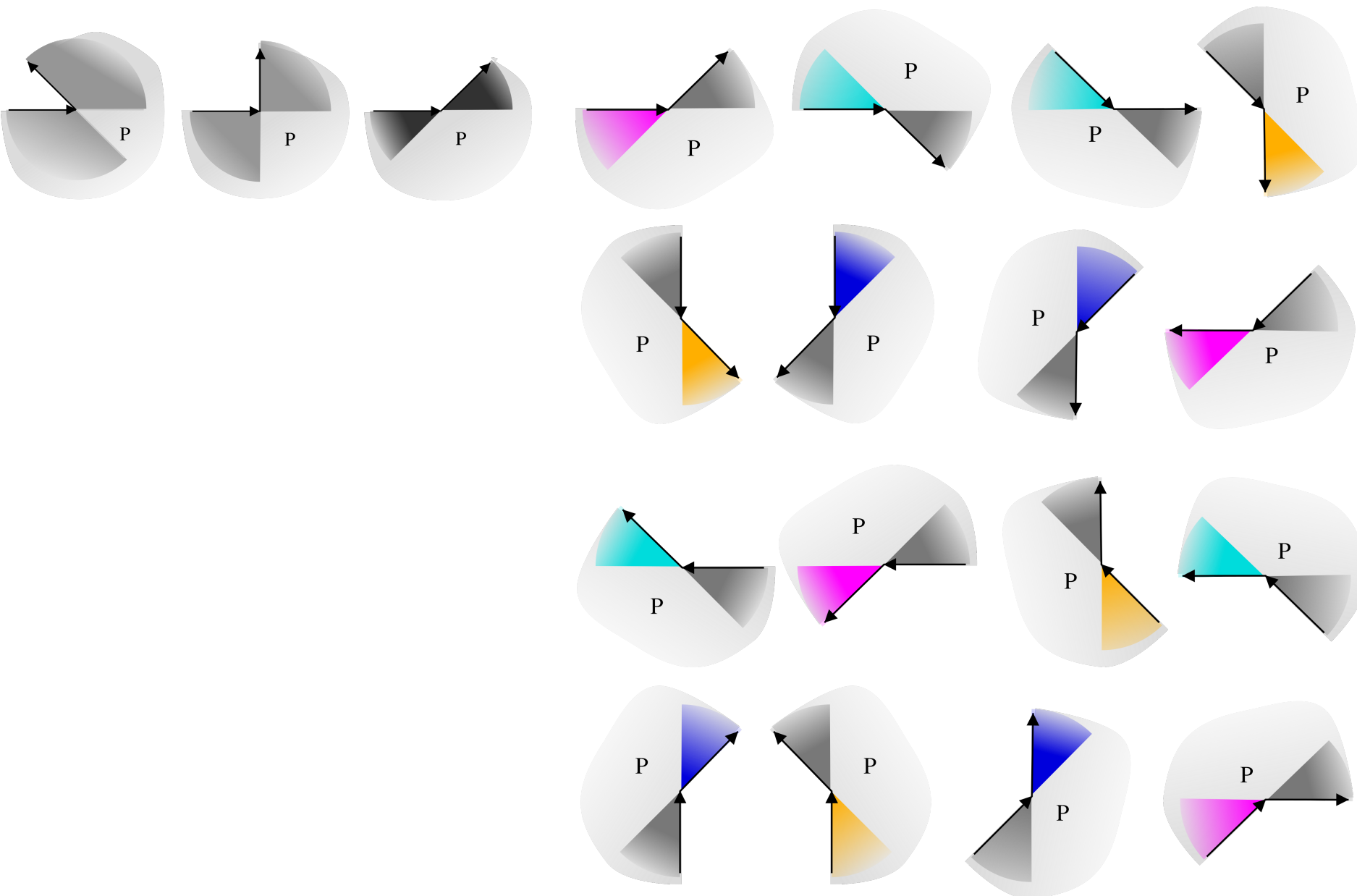
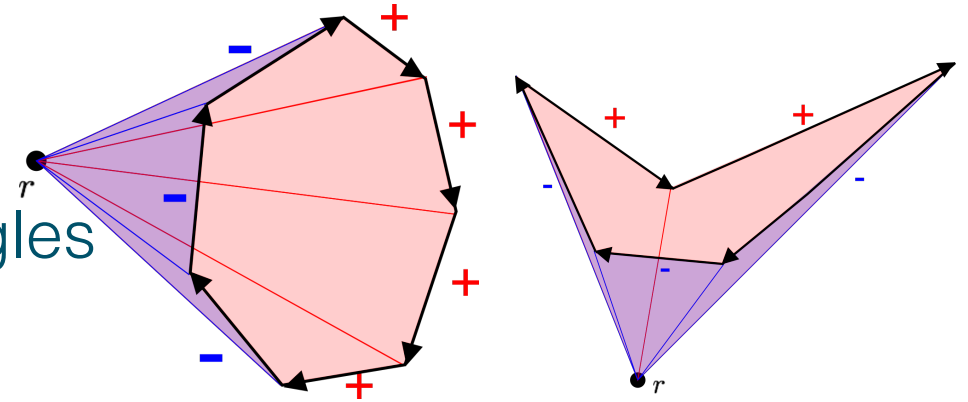
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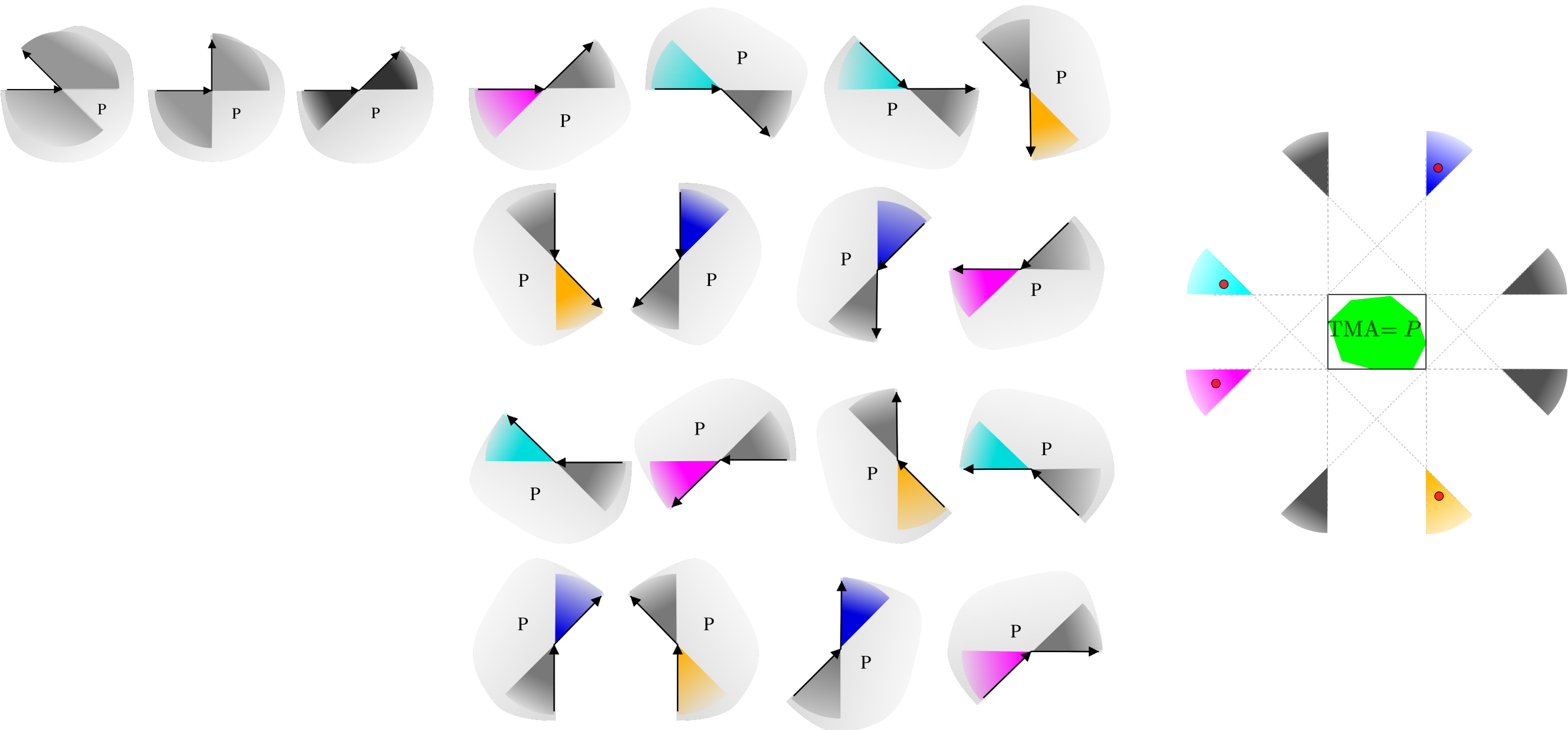
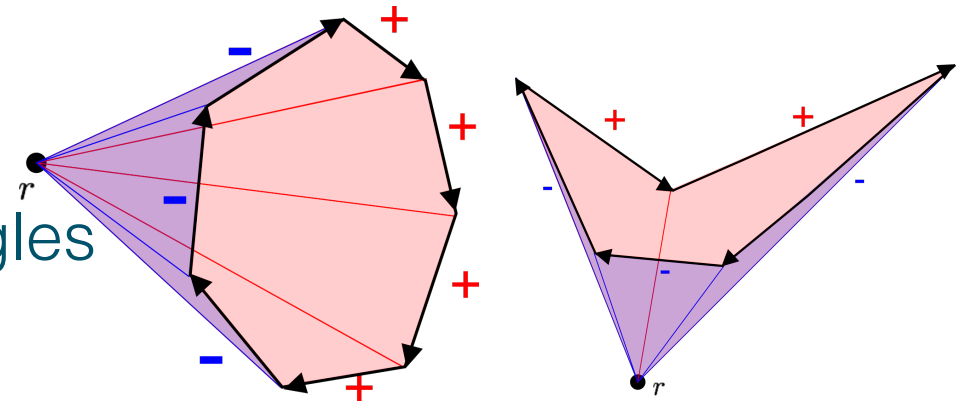
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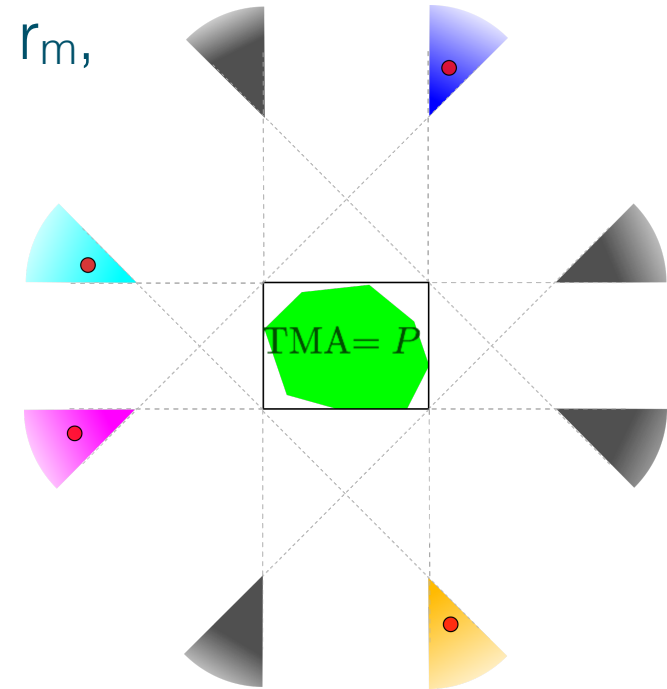


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- One reference point in each of the four colored cones: r_1, \dots, r_4 ($r = r_m$, for some $m \in M = \{1, 2, 3, 4\}$)



$$q_{j,m}^s = \frac{1}{2} \left(\sum_{i:(i,j) \in E} p_{i,j,m} y_{i,j,s} - \sum_{l:(j,l) \in E} p_{j,l,m} y_{j,l,s} \right) \quad \forall s \in \mathcal{S}, \forall j \in V, \forall m \in \mathcal{M}$$

$$qabs_{j,m}^s \geq q_{j,m}^s \quad \forall s \in \mathcal{S}, \forall j \in V, \forall m \in \mathcal{M}$$

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$$\sum_{i \in V} \sum_{j \in V} y_{i,j,s} \cdot qabs_{j,m}^s = 2 \quad \forall s \in \mathcal{S}, \forall m \in \mathcal{M}$$

$$0 \leq z_{i,j,m}^s \quad \forall i, j \in V \quad \forall s \in \mathcal{S}, \forall m \in \mathcal{M}$$

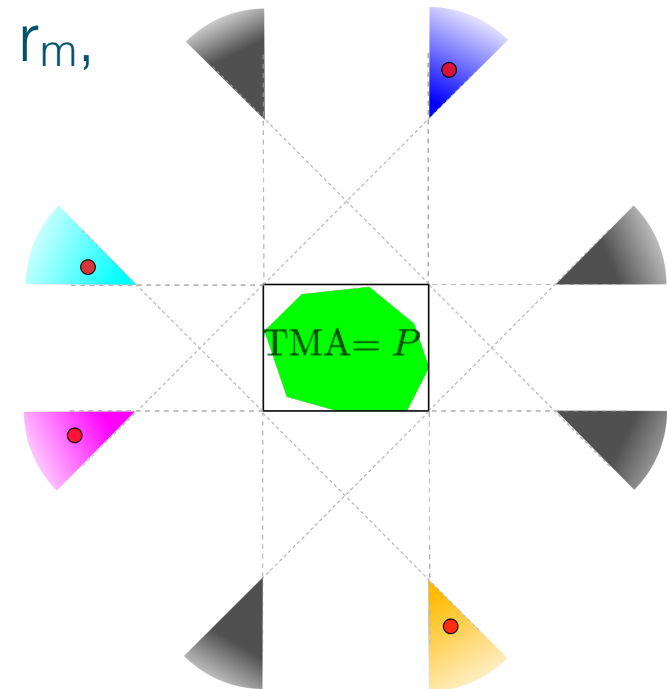
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$$z_{i,j,m}^s \leq y_{i,j,s} \quad \forall i, j \in V \quad \forall s \in \mathcal{S}, \forall m \in \mathcal{M}$$

$$z_{i,j,m}^s \geq y_{i,j,s} - 1 + qabs_{j,m}^s \quad \forall i, j \in V \quad \forall s \in \mathcal{S}, \forall m \in \mathcal{M}$$

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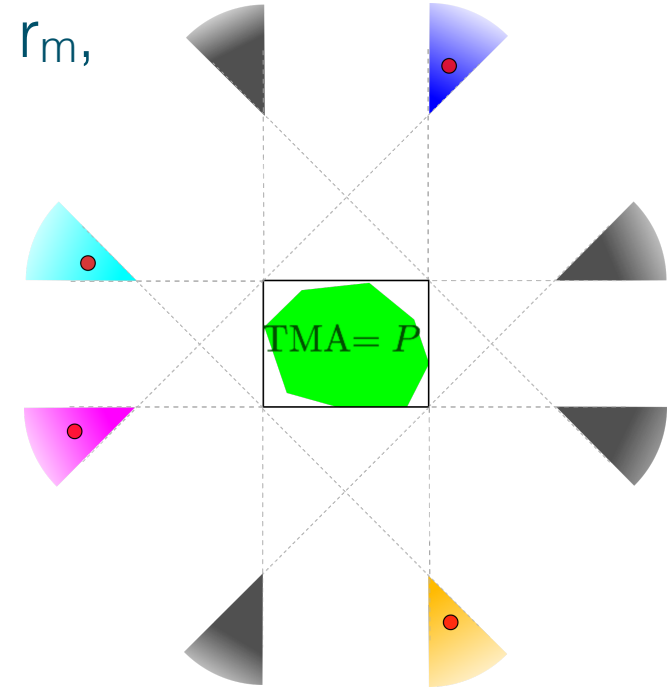
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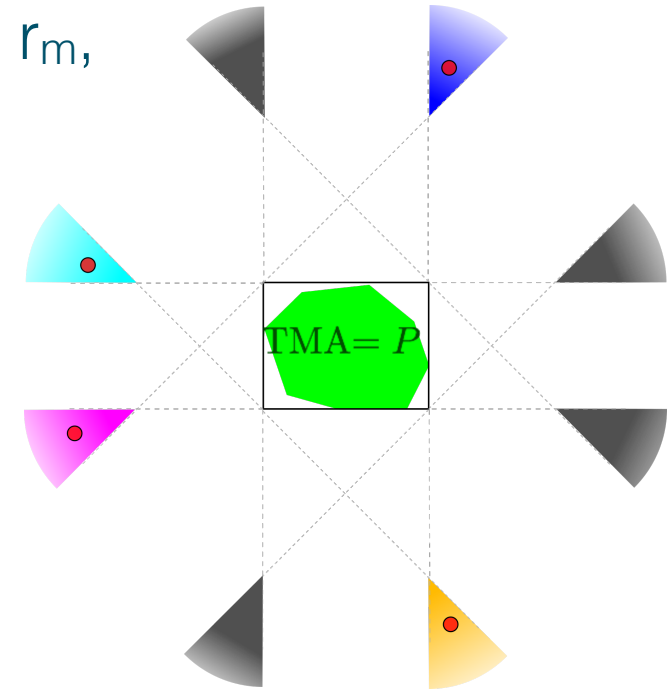
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Assigns, for each sector, a value of -1,0,1 to each vertex.

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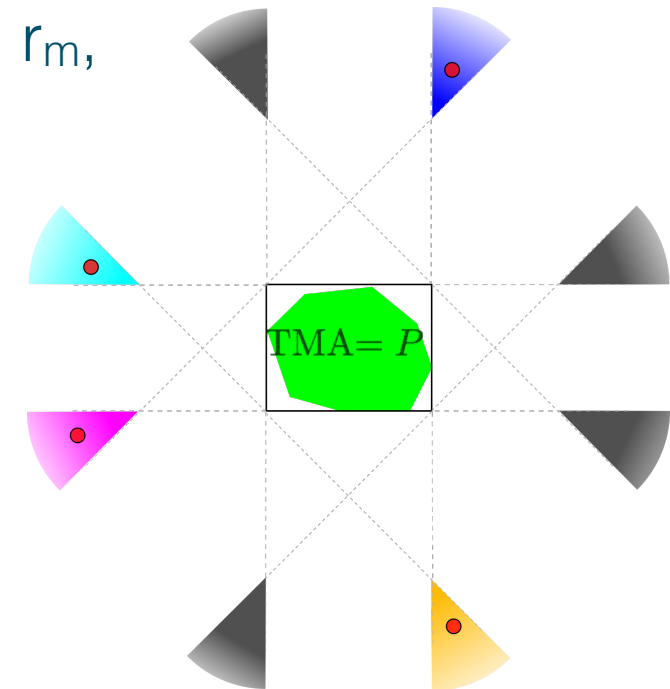
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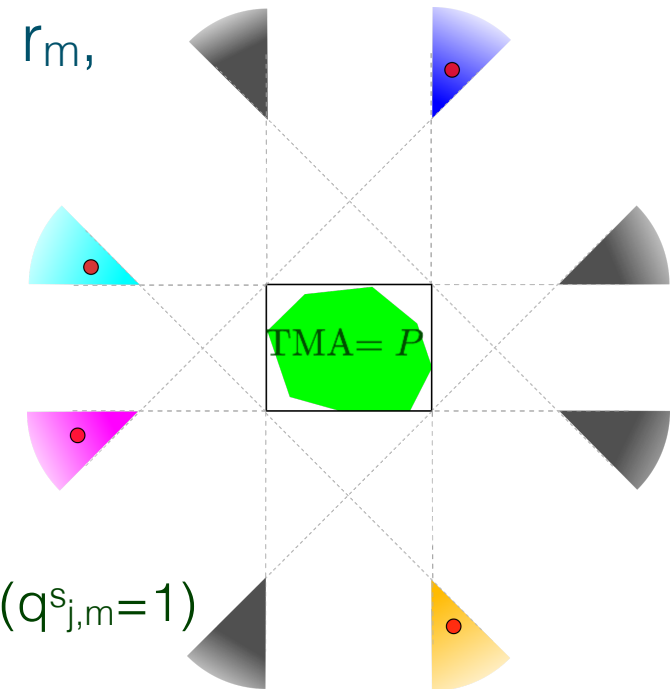
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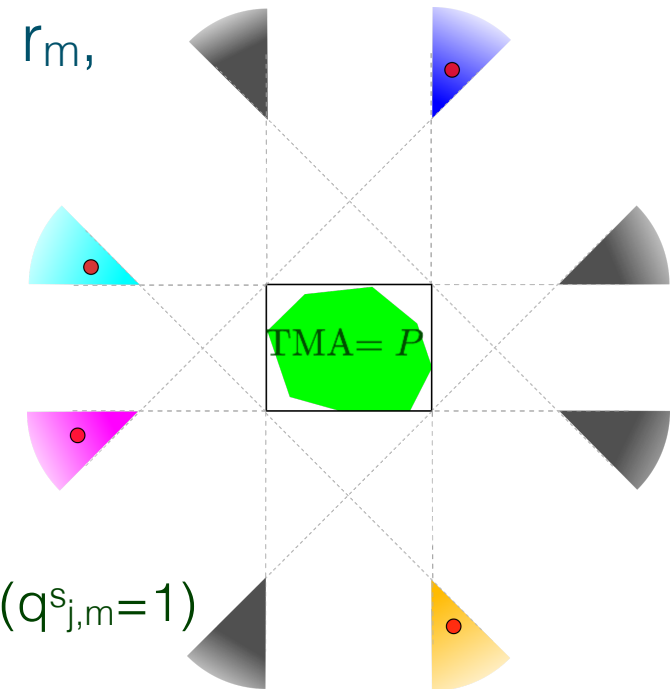
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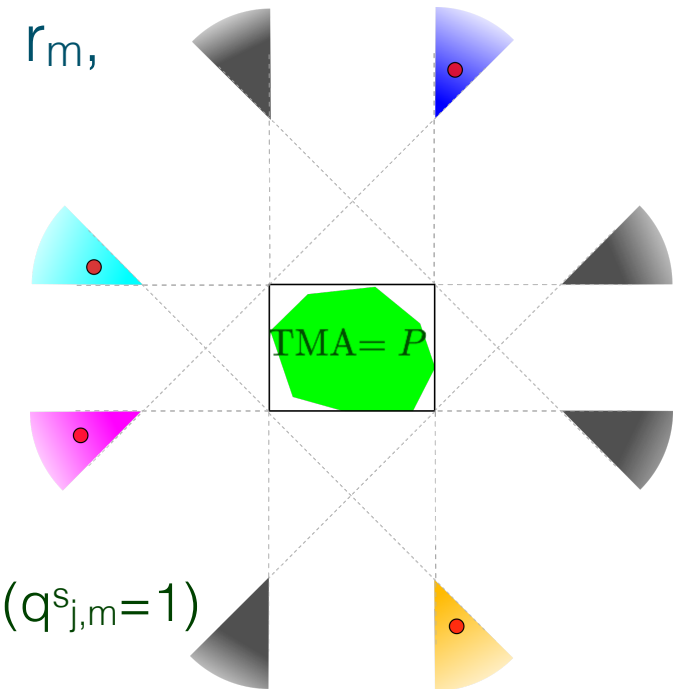
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Multiplication of two variables \rightarrow define $z_{i,j,m}^s = y_{i,j,s} * qabs_{j,m}^s$.

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$$w_{i,j} = h_i + h_j$$

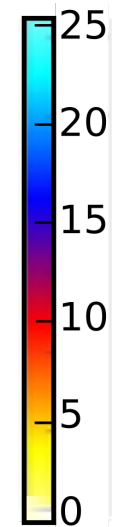
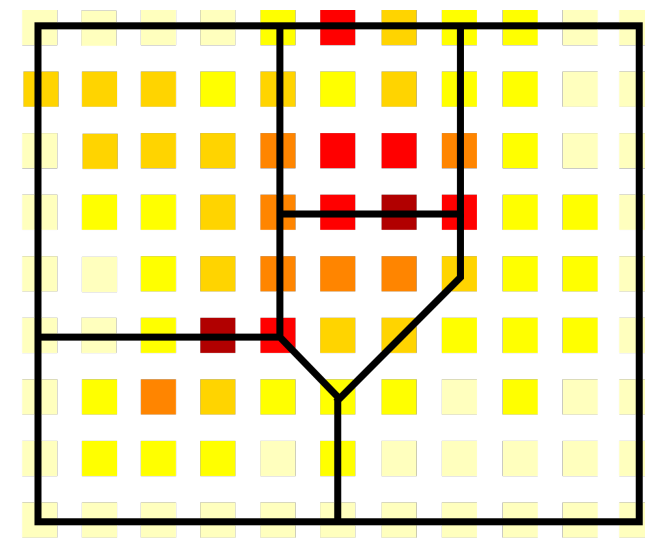
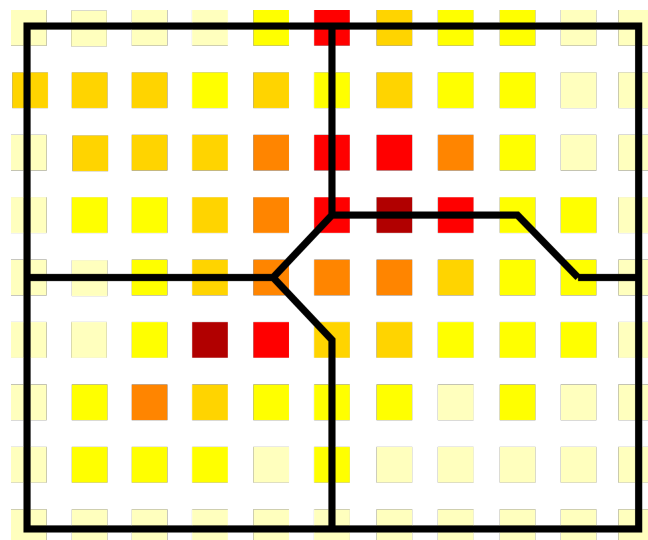
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Experimental Study: Arlanda Airport

(c) Balanced task load, (d) Connected sectors, (e) Nice shape (we use preprocessing)

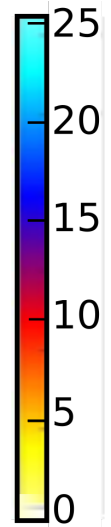
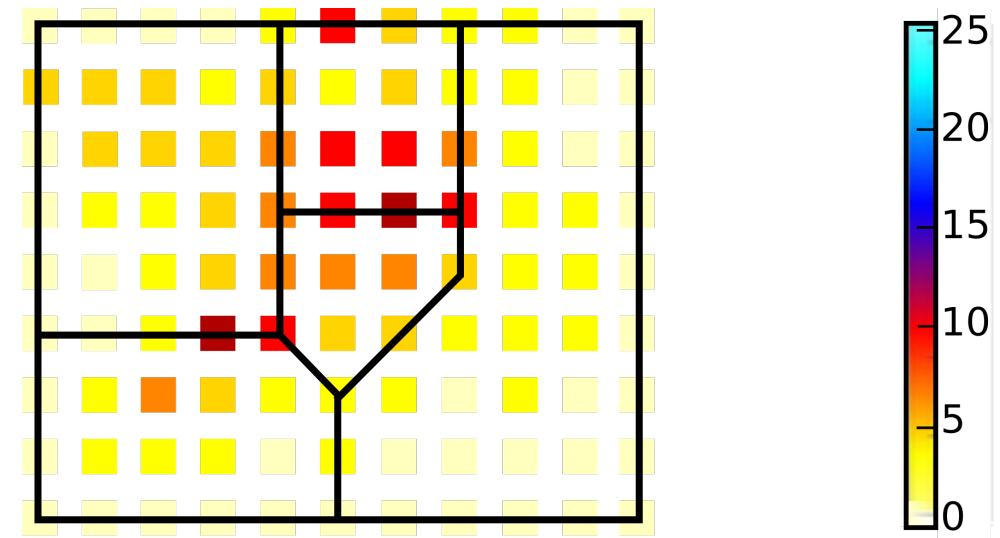
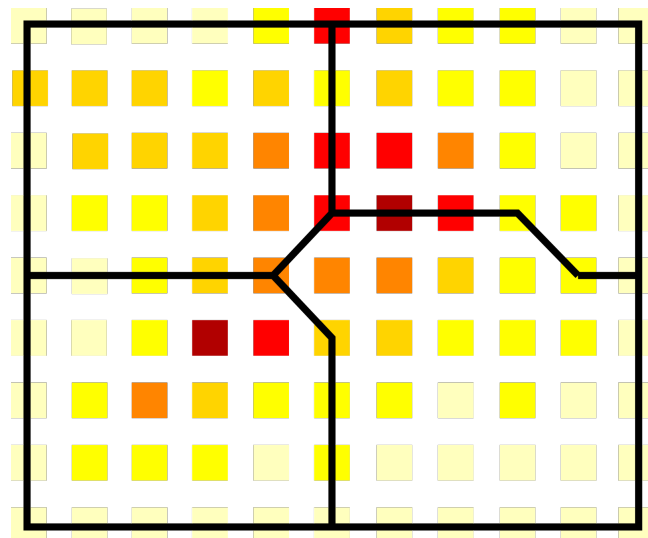
AMPL and CPLEX 12.6 on a single server with 24GB RAM and four kernels running on Linux. Each instance was run until a solution with less than 1% gap had not been found, or for a maximum of one CPU-hour. No instance finished with an optimality gap of more than 6%.

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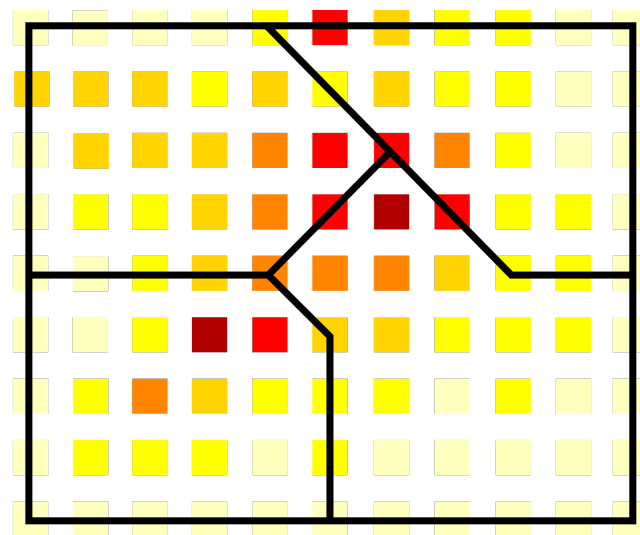


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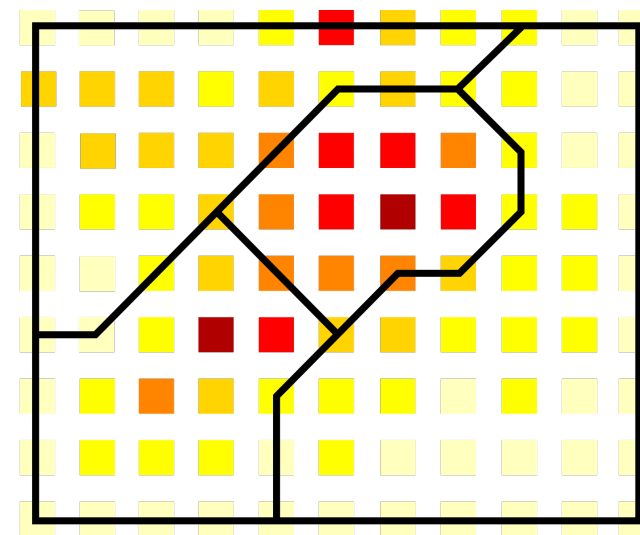


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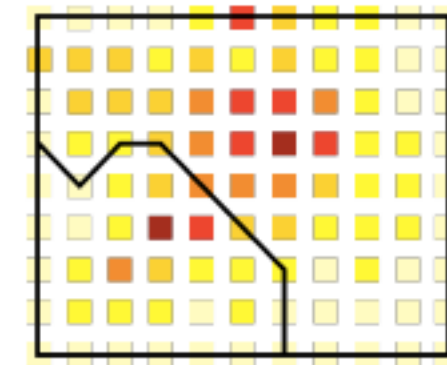
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$\leftarrow \gamma = 0.9 \quad \gamma = 0.5 \rightarrow$

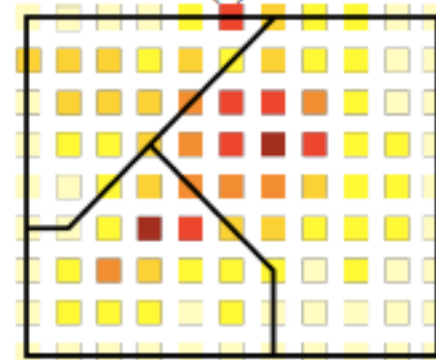


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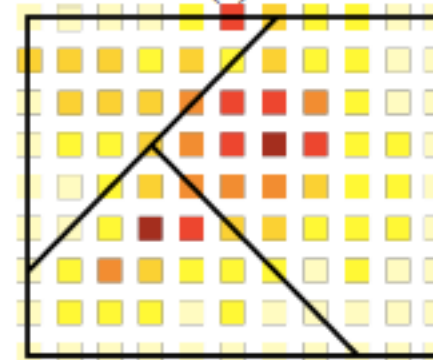
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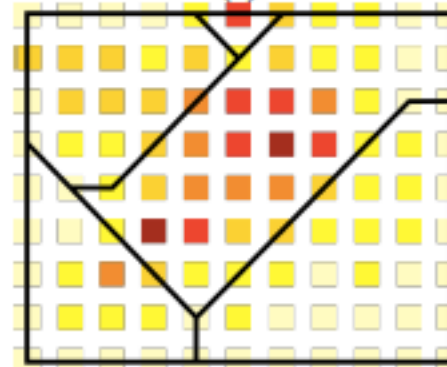
(a)



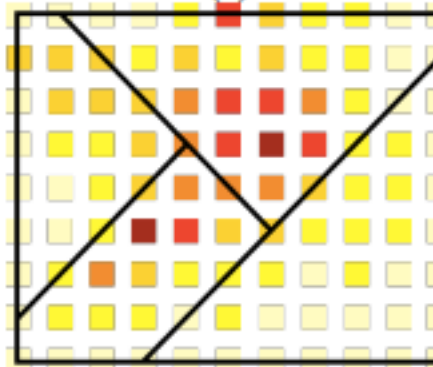
(b)



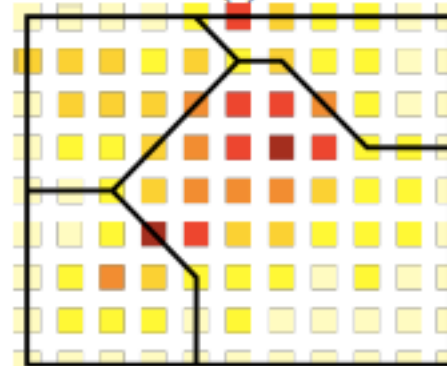
(c)



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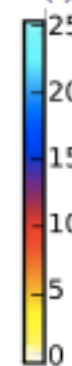


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(g)

(f)



(h)

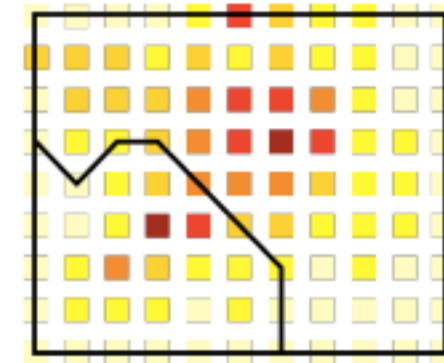
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(a)-(f): $\gamma = 0:2$, (g): $\gamma = 0:8$.

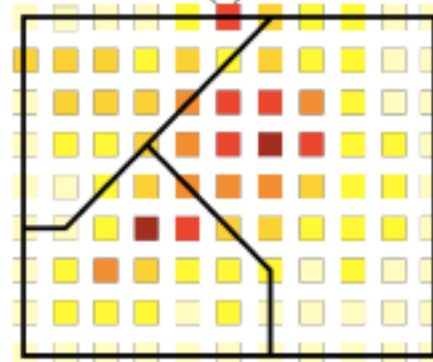
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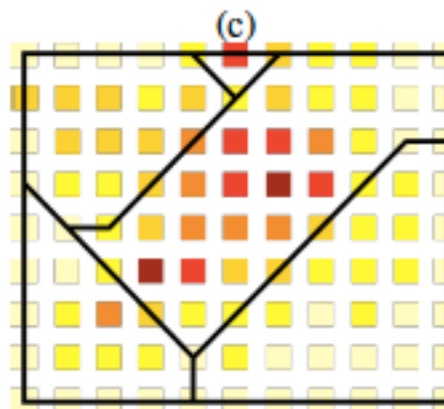
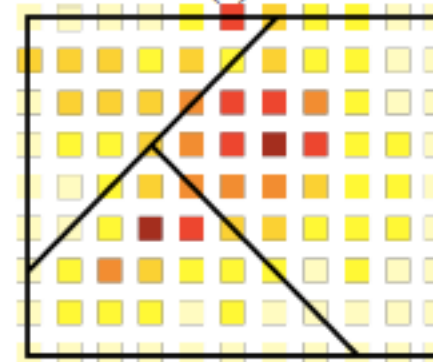
Disconnected sector →



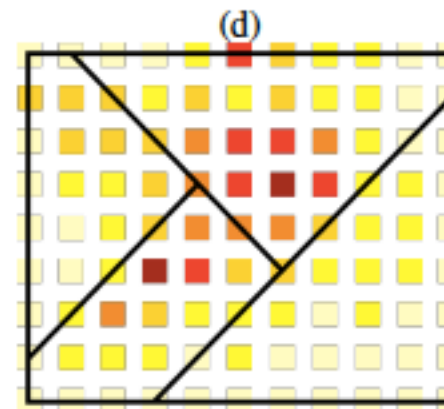
(a)



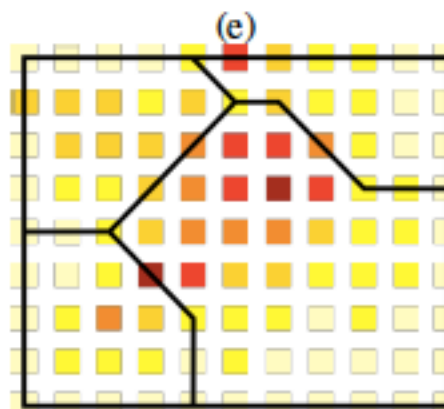
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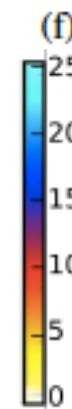
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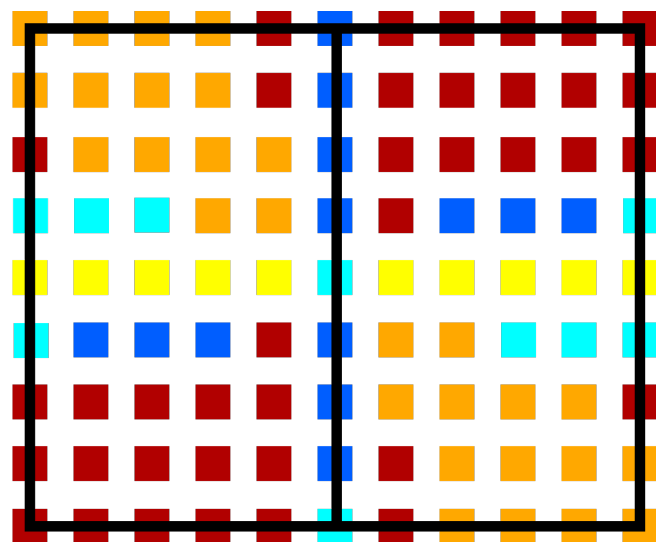
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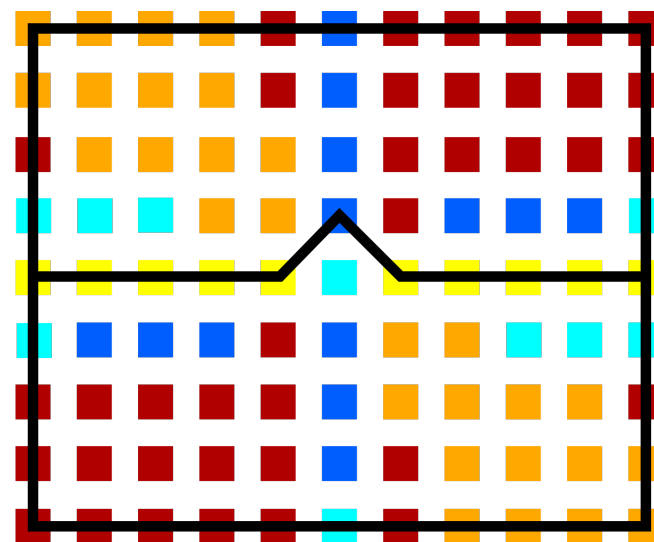
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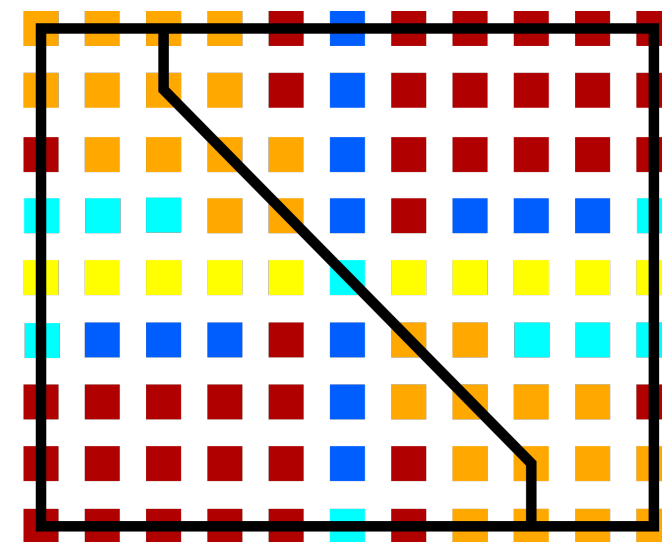
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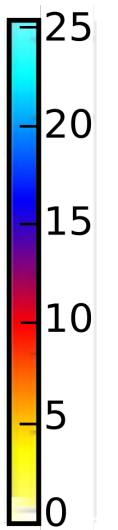
$\gamma=1$



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