### **Free Form Incident Light Fields**



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# Image Based Lighting





## Image Based Lighting





# Incident Light Fields

- Capture and Render with complex, spatially varying real world illumination
- High Dynamic Range (HDR) image sequences
- 4D Free Form Incident Light Field (ILF) representation
- Light source extraction
- Editing of the captured illumination



## Related Work

- Image Based Lighting
  - [Deb98][SSI99][UGY07][ISG\*08]
- Light Field Techniques
  - [LH96][GGSC96][UWH\*03][WJV\*05]
- HDR Imaging
  - [RWPD06][UG07]



# Spatially Varying Illumination





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#### **Reference Photograph**



# Spatially Varying Illumination



#### Rendering with a single light probe

### Capture System





# Capture System

- 25 HDR frames per second with a dynamic range of up to I:10,000,000, resolution 892x512 [UG07][UGY07]
- Hardware platform, SICK IVP Ranger-C55
- Translation stage 1.5 m<sup>3</sup>
- Position tracking sub-millimeter accuracy
- Hand-driven manual capture





# **ILF** Capture

- Assume that the scene is stationary during capture and that there are no occluding objects within the sampling volume
- Sampling of the plenoptic function as:  $P(x, y, z, \phi, \theta)$

$$B(\mathbf{x}, \vec{\omega}_o) = \int_{\forall \vec{\omega}_i} L(\mathbf{x}, \vec{\omega}_i) T(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) (\mathbf{n} \cdot \vec{\omega}_i) d\vec{\omega}_i$$



## **ILF** Capture



 26.000 irregularly spaced HDR light probes captured in the test scene ~80GB floating point image data



## **ILF** Representation













### **ILF** Representation





# **ILF** Representation

- The light rays are stored in angular buckets located at a set of 2D ILF surfaces enclosing the scene, in this case planes
- Each bucket contains a projection of the irregular sample points along the corresponding direction  $(\phi, \theta)$
- The illumination incident at a certain point from a certain direction is found by linear interpolation in the 4D ray structure  $L(u, v, \phi, \theta)$
- Stored in Delaunay triangle mesh
- No regularization





# Adaptive Decimation

- Local regions with slowly varying illumination
- Remove redundant vertices in the triangle mesh
- Standard triangle decimation [Sch97]
- A vertex is considered redundant if the error in energy introduced is less than a threshold

$$E_{Li} = \sum_{n} \int_{\Delta_n} L(u, v, \vec{\omega}_j) du dv - \sum_{m} \int_{\Delta_m} L(u, v, \vec{\omega}_j) du dv$$
$$|E_{Li}| < T$$



## **ILF** Decimation

- ~250M rays in the top plane
- T was set to 0.1% of the average radiant energy per square mm
- ~8M rays after decimation
- Data reduction 97%
- RMS 0.3%
- Total relative error 0.1%







#### Brute force rendering: 5 hours





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- Long rendering time and noisy renderings
- Noise is introduced by the stochastic sampling
- Pre-tabulated importance sampling difficult due to the large size and generality of the ILF data
- Illuminant extraction: a scene-based approach



 Represent the illumination as a residual ILF with low frequency and low contrast content and a set of concentrated high intensity Source Light Fields (SLFs) re-projected to their approximate original position in the scene

$$L(\mathbf{u}, \vec{\omega}) = L_0(\mathbf{u}_{k_0}, \vec{\omega}_{k_0}) + \sum_{n=1}^N L_n(\mathbf{u}_{k_n}, \vec{\omega}_{k_n})$$





• High energy rays can be selected from the ILF data set based on angular selections, spatial selections and thresholding





$$z_n = \arg\min_{z} \left( A(\tilde{\mathbf{u}}_{k_n}(z)) \right)$$







#### Rendering with extracted light sources: 2 minutes



#### Brute force rendering: 5 hours





#### Rendering with extracted light sources: 2 minutes



#### Extracted projector



#### Effect of residual ILF after illuminant extraction



#### Residual ILF and two extracted SLFs



#### Area light with blocker removed

- SLFs can be edited like traditional light sources, translation, rotation, color etc.
- Individual rays can also be edited in the 4D SLF data sets





- Edit collections of rays in the SLFs
- The selection of rays is similar to the extraction: angular and spatial selection and thresholding
- We model the extracted SLF as a collection of equal intensity rays and a 2D modulation function at a distance *z* from the SLF

$$L_n(\mathbf{u}_i, \vec{\omega}_j) = I_n(\mathbf{u}_i, \vec{\omega}_j) \times f_z(s, t)$$





$$L_n(\mathbf{u}_i, \vec{\omega}_j) = I_n(\mathbf{u}_i, \vec{\omega}_j) \times f_z(s, t)$$





Area light source

Blocker

 $L_n(\mathbf{u}_i, \vec{\omega}_j) = I_n(\mathbf{u}_i, \vec{\omega}_j) \times f_z(s, t)$ 





#### Synthetic removal of an occluding object



#### Editing of under-sampled flower pattern



#### Editing of under-sampled flower pattern

### Example Capture





### SLF Extraction



#### ILF and SLF data loaded in Maya



### Rendering



### Some numbers

- ~44.000 HDR images
- 256x256 angular buckets
- ~2.25G rays in total
- ~90M rays after decimation (1.8GB)
- Data reduction 96%



- 82% of the total energy was extracted to six SLFs
- The SLFs contained I3M rays, (270MB)





